# **Bisimulation for Higher-Dimensional Automata**

#### A Geometric Interpretation

#### Uli Fahrenberg

Department of Mathematical Sciences Aalborg University

Fields-Ottawa Workshop on the Geometry of Very Large Data Sets

# Outline

#### Introduction

- Parallelism vs. Mutual Exclusion
- Higher-Dimensional Automata
- The "van Glabbeek Hierarchy"
- The Link to Geometry
- 2 Simulation and Bisimulation
  - Morphisms of HDA
  - Bisimulation
- 3 The Geometry of HDA
  - Local po-spaces
  - Directed Maps

The Geometry of HDA

#### Parallelism vs. Mutual Exclusion



◆□ > ◆□ > ◆ Ξ > ◆ Ξ > 三目目 のへの

The Geometry of HDA

## Parallelism vs. Mutual Exclusion



The Geometry of HDA

#### Parallelism vs. Mutual Exclusion



< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

The Geometry of HDA

◆□ > ◆□ > ◆豆 > ◆豆 > 三日 のへぐ

#### Parallelism vs. Mutual Exclusion



The Geometry of HDA

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■□ のQ@

#### Parallelism vs. Mutual Exclusion



Real-time systems

The Geometry of HDA

#### Parallelism vs. Mutual Exclusion









<□ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ >

# **Higher-Dimensional Automata**

So a higher-dimensional automaton is a pointed precubical set

$$A = \{A_n\}$$
  
$$\delta_i^0, \delta_i^1 : A_n \to A_{n-1} \quad (i = 1, \dots, n)$$

#### (The point $* \in A_0$ is the *initial state*.)

Note: For *labeled* HDA, the easiest is to work in a comma category of pointed precubical sets over a category of certain special *alphabet precubical sets* (which are  $\infty$ -tori), but we shall not need this here.



(Pratt, Van Glabbeek 1991)

# **Higher-Dimensional Automata**

So a higher-dimensional automaton is a pointed precubical set

$$A = \{A_n\}$$
  
$$\delta_i^0, \delta_i^1 : A_n \to A_{n-1} \quad (i = 1, \dots, n)$$

(The point  $* \in A_0$  is the *initial state*.)

Note: For *labeled* HDA, the easiest is to work in a comma category of pointed precubical sets over a category of certain special *alphabet precubical sets* (which are  $\infty$ -tori), but we shall not need this here.



(Pratt, Van Glabbeek 1991)

The Geometry of HDA

#### The "van Glabbeek Hierarchy"



・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・
 ・

## The Link to Geometry

Geometric realisation:

precubical sets  $\longrightarrow$  topological spaces

Holes in the space  $\iff$  Mutual exclusion in the HDA

Has been employed by various people, Goubault, Fajstrup, Raussen, ...

My contribution: Bisimilarity of HDA is related to a path-lifting property of their geometric realisations

## Morphisms of HDA

#### Morphisms of HDA should be *simulations*:

 $A \rightarrow B$  iff whatever A can compute, B can compute, too.

So what is a computation?



\*

So simulations are just morphisms of pointed precubical sets.

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■□ のQ@

## Morphisms of HDA

Morphisms of HDA should be *simulations*:

 $A \rightarrow B$  iff whatever A can compute, B can compute, too.

So what is a computation?



\*

So simulations are just morphisms of pointed precubical sets.

## Morphisms of HDA

Morphisms of HDA should be *simulations*:

 $A \rightarrow B$  iff whatever A can compute, B can compute, too.

So what is a computation?



\*

So simulations are just morphisms of pointed precubical sets.

The Geometry of HDA

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■□ のQ@

## Morphisms of HDA

Fine, so the category of HDA (over a fixed alphabet *L*) is just the category of pointed precubical sets.

Note: For the category of HDA over varying alphabets, things are more complicated. One needs to introduce "*idle transitions*" and to work with *cubical* sets instead (i.e. precubical sets with degeneracies).

To be precise: The full category of HDA consists of diagrams like this one, with *A*, *A'*, *L*, *L'* precubical sets, black arrows precubical morphisms, and red arrows *cubical* morphisms.

We will not need this here.

Simulation and Bisimulation  $_{\odot \bullet \odot}$ 

The Geometry of HDA

#### Morphisms of HDA

Fine, so the category of HDA (over a fixed alphabet L) is just the category of pointed precubical sets.

Note: For the category of HDA over varying alphabets, things are more complicated. One needs to introduce *"idle transitions"* and to work with *cubical* sets instead (i.e. precubical sets with degeneracies).

To be precise: The full category of HDA consists of diagrams like this one, with *A*, *A'*, *L*, *L'* precubical sets, black arrows precubical morphisms, and red arrows *cubical* morphisms.

We will not need this here.



Two HDA *A*, *B* are *bisimilar* if whatever *A* can compute, *B* can also compute, and *vice versa*.

So a morphism  $f : A \rightarrow B$  is a bisimulation if for any  $a \in A$  and for any computation starting in f(a), there is a computation starting in *a* which maps to the computation in *B*.

Or equivalently, if

 $\forall a \in A, \forall c' \in B : f(a) = \delta_i^0 c',$  $\exists c \in A : c' = f(c), a = \delta_i^0 c$ 

Two HDA *A*, *B* are *bisimilar* if whatever *A* can compute, *B* can also compute, and *vice versa*.

So a morphism  $f : A \rightarrow B$  is a bisimulation if for any  $a \in A$  and for any computation starting in f(a), there is a computation starting in *a* which maps to the computation in *B*.

Or equivalently, if

$$\forall \mathbf{a} \in \mathbf{A}, \forall \mathbf{c}' \in \mathbf{B} : f(\mathbf{a}) = \delta_i^0 \mathbf{c}', \qquad \mathbf{B} \\ \exists \mathbf{c} \in \mathbf{A} : \mathbf{c}' = f(\mathbf{c}), \mathbf{a} = \delta_i^0 \mathbf{c}$$

Two HDA *A*, *B* are *bisimilar* if whatever *A* can compute, *B* can also compute, and *vice versa*.

So a morphism  $f : A \rightarrow B$  is a bisimulation if for any  $a \in A$  and for any computation starting in f(a), there is a computation starting in *a* which maps to the computation in *B*.

Or equivalently, if

$$\forall \mathbf{a} \in \mathbf{A}, \forall \mathbf{c}' \in \mathbf{B} : f(\mathbf{a}) = \delta_i^0 \mathbf{c}',$$
$$\exists \mathbf{c} \in \mathbf{A} : \mathbf{c}' = f(\mathbf{c}), \mathbf{a} = \delta_i^0 \mathbf{c}$$

Two HDA *A*, *B* are *bisimilar* if whatever *A* can compute, *B* can also compute, and *vice versa*.

So a morphism  $f : A \rightarrow B$  is a bisimulation if for any  $a \in A$  and for any computation starting in f(a), there is a computation starting in *a* which maps to the computation in *B*.

Or equivalently, if

$$\forall a \in A, \forall c' \in B : f(a) = \delta_i^0 c',$$
$$\exists c \in A : c' = f(c), a = \delta_i^0 c$$



#### Local po-spaces

The geometric realisation of a precubical set is a local po-space; a topological space with a relation  $\leq$  which is

- reflexive,
- antisymmetric,

#### • locally transitive, and locally closed.

(i.e. we have a cover  $U = \{U_{\alpha}\}$  of X such that  $\leq$  is transitive and closed in each  $U_{\alpha}$ .)



< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □

#### Local po-spaces

The geometric realisation of a precubical set is a local po-space; a topological space with a relation  $\leq$  which is

- reflexive,
- antisymmetric,
- *locally* transitive, and *locally* closed.
   (i.e. we have a cover U = {U<sub>α</sub>} of X such that ≤ is transitive and closed in each U<sub>α</sub>.)



## The Main Result

A dimap  $f : X \rightarrow Y$  is a continuous mapping which is *locally increasing*:

 $\forall x \in X, \exists U \ni x : \forall x_1 \leq x_2 \in U, f(x_1) \leq f(x_2) \in Y$ 

A dipath in X is a dimap  $\vec{l} \rightarrow X$ .



The Geometry of HDA ○○●

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■□ のQ@

# The Main Result

Theorem:  $f : A \to B$  is a bisimulation if and only if  $|f| : |A| \to |B|$  has the dipath-lifting property



- connection to (directed) fibrations, obstruction theory

# The Main Result

Theorem:  $f : A \rightarrow B$  is a bisimulation if and only if  $|f| : |A| \rightarrow |B|$  has the dipath-lifting property

Key of proof: For any dipath, there is a unique computation through (the geometric realisation of) which it "runs." [Fajstrup 2003]



Only holds for geometric and locally finite HDA.

# The Main Result

Theorem:  $f : A \rightarrow B$  is a bisimulation if and only if  $|f| : |A| \rightarrow |B|$  has the dipath-lifting property

Key of proof: For any dipath, there is a unique computation through (the geometric realisation of) which it "runs." [Fajstrup 2003]



Only holds for geometric and locally finite HDA.

Bibliography

# Equivalence of Computations

#### Adjacency of computations:



*Equivalence* of computations := equivalence generated by adjacency. [van Glabbeek 1991]

# Bisimulation up to Equivalence

A morphism  $f : A \rightarrow B$  is called a bisimulation up to equivalence if for any  $a \in A$  and for any computation starting in f(a), there is a computation starting in *a* which maps to a computation in *B* that is *equivalent* to the given one.

**Conjecture:**  $f : A \rightarrow B$  is a bisimulation up to equivalence if and only  $|f| : |A| \rightarrow |B|$  lifts dipaths *up to dihomotopy*:

$$0 \longrightarrow |A|$$

$$\int_{q}^{p^{-\pi}} |f| \qquad q \simeq |f| \circ p$$

$$\vec{l} \xrightarrow{q} |B|$$

# An Application to Topology

**Conjecture:** For any geometric, locally finite precubical set *A*, there exists a precubical set *B* such that |B| is the universal (directed) covering space of |A|.

Key idea: The cubes of *B* are the equivalence classes of computations of *A*.

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■□ のQ@

# Thank You!

Uli Fahrenberg Ph.D. student, Aalborg University, Denmark (currently looking for job opportunities ...)

> uli@math.aau.dk http://www.math.aau.dk/~uli

Outlook	Thank You!	Bibliography	Advertisement
000			

# Selected Bibliography I

- V. Pratt, *Modeling Concurrency with Geometry*. Proc. 18th ACM Symposium on Principles of Programming Languages, 1991.
- R. van Glabbeek, *Bisimulations for Higher Dimensional Automata*. Email message, 1991.
- R. van Glabbeek, *On the Expressiveness of Higher Dimensional Automata*. Proc. EXPRESS 2004, to be published.
- E. Goubault, *The Geometry of Concurrency*. Ph.D. thesis, 1995.
- L. Fajstrup, E. Goubault, M. Raussen, *Algebraic Topology and Concurrency*, 1999. Accepted for publication in Theor.Comp.Sci.

◆□▶ ◆□▶ ▲□▶ ▲□▶ ■□ のQ@

# Selected Bibliography II

- L. Fajstrup, *Dipaths and Dihomotopies in a Cubical Complex*. Adv.Appl.Math., to appear.
- U. Fahrenberg, *A Category of Higher-Dimensional Automata*. Proc. FOSSACS 2005, to appear.

#### Advertisement

# Geometry and Topology in Concurrency 2005 San Francisco 21 August 2005

# Workshop on Algebraic Topology in Concurrency Aalborg, Denmark August 2005 (planned)